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$x + b + \ln(x + b) + k = \ln(x + b + (x + b) + k = \ln(2(x + b)) + k = \ln(x + b) + \ln 2 + k$  Thus our earlier formula works in the case that  $b^2 = c$  and  $x + b > 0$ , where we take  $k^0 = k + \ln 2$  (which we may do, as they are arbitrary constants). Next, when  $x + b < 0$ , direct integration yields:  $Z \int p \, x^2 + 2bx + b \, dx = Z \int (x + b) \, dx = Z$ .

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The solutions of this quadratic are given by  $x = 1 \pm \sqrt{1 + 4a^2}$ ; and these will be real solutions of if and only if  $x > 0$  and  $a x > 0$ , that is  $0 \leq x \leq a$ . But as  $a^2 = x$ , we will always have  $a x > 0$  for real solutions of the quadratic, so we need only check that  $x > 0$ . For a solution to  $()$ , we therefore require the plus sign in the

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First, draw a diagram: The position vector of point P is:  $x = a \sin \theta + a \cos \theta$  and the velocity vector is:  $\dot{x} = a \cos \theta - a \sin \theta$ . The speed is given by  $v^2 = \dot{x}^2 = a^2 (\cos^2 \theta + \sin^2 \theta) = a^2$ .

**STEP Support Programme-Mechanics-STEP Questions-Solutions—**

Hints & Solutions for Paper 9470 (STEP II) June 2012 Question 1 To be honest, the binomial expansions of  $(1 + x)^n$ , in the cases  $n = 1, 2$ , are used so frequently within AS- and A-levels that they should be familiar to all candidates taking STEPs. Replacing  $x$  by  $xk$  is no great further leap.

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